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Quantity	Variable	Unit	Unit Symbol
Length	l, d, r, ∆x	meter	m
Mass	m	kilogram	kg
Time	t	second	S
Energy	E	Joule	J
Power	Р	Watt	W
Thermodynamic temperature	Т	kelvin	K
Electric current	I	ampere	Α
Electric charge	q	Coulomb	C
Electric potential (voltage)	ν, Δ ν	Volt	V
Electric resistance	R	Ohm	Ω
Force	F	Newton	N
Pressure	Р	pascal	Pa
Frequency	f	Hertz	Hz
Angles/Angular Displacement	Δ θ	radian	rad

 $\frac{\text{Kinematic Equations}}{\Delta x = x_f - x_0}$

 $\frac{\text{If not accelerating:}}{v = \frac{\Delta x}{t}}$

 $\frac{\text{If accelerating:}}{a = {}^{\Delta v}/_t = {}^{(v_f} - {}^{v_0})/_t}$ $\Delta x = {}^{1/2} (v_0 + v_f)t$ $\Delta x = v_0 t + {}^{1/2} at^2$ $v_f = v_0 + at$ $v_f^2 = v_0^2 + 2a\Delta x$ Free Fall

 $g = -9.81 \text{ m/s}^2$

Angles/Angular Displacement		Δ0	radian	
Symbol	Meaning	Value]
G	billion	x 10 ⁹		• •
м	million	x 10 ⁶		
k	thousand	x	10 ³	-
с	hundredth	×	10 ⁻²	-
m	thousandth	×	10 ⁻³	
	millionth			
•				-
	Symbol G M k c	Symbol Meaning G billion M million M thousand c hundredth m thousandth μ millionth	Symbol Meaning Value G billion x M million x k thousand x c hundredth x m thousandth x μ millionth x	SymbolMeaningValueGbillionx 109Mmillionx 106kthousandx 103chundredthx 10-2mthousandthx 10-3μmillionthx 10-6

Trigonometry

 $tan\theta = opposite/adjacent$

 $\sin\theta = \text{opposite/hypotenuse}$

 $\cos\theta = adjacent/hypotenuse$

hypotenuse² = $opposite^{2} + adjacent^{2}$

Dynamics Formulas $F_G = mg$ Flat surface: $F_N = -F_G = -mg$ Inclined surface: $F_N = -F_G(\cos \theta) = -mg(\cos \theta)$ $F_{s,max} = \mu_s F_N$ $F_k = \mu_k F_N$ $F_{elastic} = -k\Delta x$ F_{net} = ma Energy Formulas $KE = \frac{1}{2} mv^2$ $PE_e = \frac{1}{2} kx^2$ $PE_q = mgh$ $W = F \Delta x (\cos \theta)$ $\mathbf{W} = \Delta \mathbf{P} \mathbf{E}_{g} + \Delta \mathbf{P} \mathbf{E}_{e} + \Delta \mathbf{K} \mathbf{E}$ $W = mg(h_f - h_0) + \frac{1}{2}k(x_f^2 - x_0^2) + \frac{1}{2}m(v_f^2 - v_0^2)$ $\mathsf{PE}_{g0} + \mathsf{PE}_{e,0} + \mathsf{KE}_{0} = \mathsf{PE}_{g,f} + \mathsf{PE}_{e,f} + \mathsf{KE}_{f}$ $mgh_0 + \frac{1}{2} kx_0^2 + \frac{1}{2} mv_0^2 = mgh_f + \frac{1}{2} kx_f^2 + \frac{1}{2} mv_f^2$ Power = E/t = W/t = Fv

 $Power = F_{t} = w_{t} = Fv$ $\frac{Momentum Formulas}{p = mv}$ $Ft = \Delta p = m\Delta v$ $P_{total,intial} = p_{total, final}$ $m_{a}v_{a,0} + m_{b}v_{b,0} = m_{a}v_{af} + m_{b}v_{bf}$ $KE_{total,intial} = \frac{1}{2}m_{1}v_{1,0}^{2} + \frac{1}{2}m_{2}v_{2,0}^{2}$ $KE_{total, final} = \frac{1}{2}m_{1}v_{1,f}^{2} + \frac{1}{2}m_{2}v_{2,f}^{2}$ $\% \text{ lost} = [(KE_{f} - KE_{0})/KE_{0}] \times 100$

opposite





